

# Kinematic Equations for Linear Motion

(For constant acceleration *ONLY*)

\*\* To select the appropriate equation to solve a particular problem:

- 1) List what quantities are given - (*will be 3*)
- 2) List what is being asked for - (*will be 1*).
- 3) Find the equation in the table that contains all 4 involved quantities.

Equation	Involved Quantities	Unneeded Quantity
1) $v = v_o + at$	$v_o, v, a, t$	$\Delta x$
2) $v^2 = v_o^2 + 2a\Delta x$	$\Delta x, v, v_o, a$	$t$
3) $\Delta x = v_o t + \frac{1}{2}at^2$	$\Delta x, v_o, a, t$	$v$
4) $\Delta x = \frac{1}{2}(v + v_o)t$	$\Delta x, v, v_o, t$	$a$
5) $\Delta x = vt - \frac{1}{2}at^2$	$\Delta x, v, a, t$	$v_o$

\*\*  $\Delta x = (x - x_o)$

\*\* **These equations work for motion in ANY one direction (x, y, or z)**

\*\* **If  $\Delta x$  also represents the *total* distance in *only* 1 direction, you can replace  $\Delta x$  with  $d$  (for distance) and then think of  $v$  and  $v_o$  in terms of *speed* rather than *velocity***